Real Version of Calculus of Complex Variable (I): Weierstrass Point of View*

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Abstract

A very small amount of Kähler algebra (i.e. Clifford algebra of differential forms) in the real plane makes x+ydxdy emerge as a factor between the differentials of the Cartesian and polar coordinates, largely replacing the concept of complex variable. The integration on closed curves of closed 1-forms on multiply connected regions takes us directly to a real plane version of the theorem of residues. One need not resort to anything like differentiation and integration with respect to x+ydxdy. It is a matter of algebra and integration of periodic functions. We then derive Cauchy's integral formulas, including the ones for the derivatives. Additional complex variable theory of general interest for phyicists are then trivial.

The approach is consistent with the Wierstrass point of view: power series expansions, even if explicit expressions are not needed. By design, this approach cannot replace integrations that yield complex results. These can be obtained with an approach based on the Cauchy point of view, where the Cauchy-Riemann conditions come first and the theorem of residues comes last (Paper to follow).

1 Introduction

In this paper, we reach the theorem of residues on multiply connected domains of the real plane, thus bringing Cauchy's theory to the fold of real

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analysis. It results from a simple and direct continuation of a corollary to Stokes theorem in not simply connected regions generated by the removal of poles of integrands. We assume that these are isolated ones.

The key element in this as in a follow-up paper is the replacement of z with the differential form x + ydxdy. Readers who know if credit has to be given to others for developing similar work (without differentiations with respect to a Clifford variable!), please contact this author.

In this Weierstrass approach, we get the theorem of residues as if the Cauchy calculus had never existed. We then go into developing Cauchy's special integral formulas. We use the term special since it does not apply to (the real form) of imaginary integrals. The more general framework in next paper's approach, which we shall call Cauchy's, will allow us to obtain those "complex results". The perspective of those approaches is due to Henri Cartan [1], but for the fact that our algebra is real and no new concept of differentiation is needed.

This paper can be used for a two hour course. In the first hour, one would derive the theorem of residues and pose a set of exercise for practice. In a second hour, one would resolve problems that students might have had solving those exercises and would present Cauchy's integral formulas, with applications. But this should not distract us from the conceptual progress made.

The words in the language of integration are differential forms. For the use that most physicists make of the theory of complex variable, it is a historical accident that happened at a time when differential forms were not known (much less their Clifford algebras). The genius of Cauchy allowed him to get powerful results without the right tools to address them.

2 Extension of the real calculus in the plane

2.1 Essence of the theorem of residues

In the real plane, Stokes theorem allows one to replace arbitrary integration contours (defined here as closed curves, not as boundaries) with circles centered at isolated singularities. In addition, we can make the radius go towards zero without changing the value of the integral. Hence the problem of integration becomes one of computing limits of integrals that depend only on the angular coordinate.

Let α be a closed scalar-valued differential 1-form, i.e. $d\alpha = 0$. This is equivalent to the condition of zero curl of a vector field with the same components as α . In polar coordinates, α is written as

$$\alpha = h(\rho, \phi)d\rho + j(\rho, \phi)d\phi. \tag{1}$$

We wish to integrate α on curves that enclose only isolated poles but go through none. We may replace the integral with a sum of non overlapping circles with the same orientation, each centered at and containing only one pole. When limits exist, the fact that ρ remains constant on centered circles (indicated with the subscript 0, and omitting a subscript to label the poles) allows us to write that integral with a sum of integrals over the small circles,

$$\oint \alpha = \sum_{\rho_0 \to 0} \oint j(\rho_0, \phi) d\phi.$$
(2)

The idea behind the theorem of residues is that integration of the Fourier power series of $j(\rho_0,\phi)$ over 2π implies

$$\oint \alpha = 2\pi \sum_{\rho_0 \to 0} \lim_{\rho_0 \to 0} a_0, \tag{3}$$

where a_0 represents the constant term in the Fourier series of the expansion of $j(\rho_0,\phi)$ around each pole. But its computation involves performing the integral that one intends to solve. Clifford algebra allows us to easily convert this trigonometric problem into one involving Cartesian coordinates. Its solution then lies in obtaining a limit. That is in a nutshell the theorem of residues.

2.2 Theorem of residues

The Kähler algebra (i.e. Clifford algebra of differential forms) is defined by

$$dx^i dx^j + dx^j dx^i = 2g^{ij}, (4)$$

where g^{ij} is the metric [2]. In Cartesian and polar coordinates in any real plane:

$$(dx)^2 = (dy)^2 = (d\rho)^2 = 1, \qquad (d\phi)^2 = \frac{1}{\rho^2}$$
 (5)

$$dxdy = -dydx, (dxdy)^2 = -1. (6)$$

The complex looking inhomogeneous differential form

$$z \equiv x + y dx dy,\tag{7}$$

emerges from the relation between $(d\rho, d\phi)$ and (dx, dy):

$$d\phi = \frac{xdy - ydx}{x^2 + y^2} = \frac{x - ydxdy}{x^2 + y^2}dy = \frac{1}{x + ydxdy}dy = \frac{1}{z}dy,$$
 (8)

$$d\rho = \frac{xdx + ydy}{(x^2 + y^2)^{1/2}} = \rho \frac{x - ydxdy}{x^2 + y^2} dx = \frac{\rho}{x + ydxdy} dx = \frac{\rho}{z} dx.$$
 (9)

By virtue of the second equation (6), it is clear that

$$z^{\pm m} = (x + ydxdy)^{\pm m} = \rho^{\pm m}e^{m\phi dxdy} = \rho^{\pm m}(\cos m\phi \pm dxdy\sin m\phi), \quad (10)$$

for integer m.

Like z itself, functions F(z) take values in the even subalgebra, whose elements are of the form

$$u(x,y) + v(x,y)dxdy, (11)$$

This subalgebra is commutative. In the full algebra, we have

$$(u + vdxdy)\alpha = \alpha(u + vdxdy)^*, \qquad (u + vdxdy)^* \equiv u - vdxdy, \qquad (12)$$

and, in particular,

$$z^* = x - y dx dy, \quad z^* = \rho^2 / z \tag{13}$$

Given two differential 1-forms α and β , define

$$\alpha \cdot \beta \equiv \frac{1}{2}(\alpha\beta + \beta\alpha). \tag{14}$$

One readily obtains

$$d\rho \cdot d\phi = 0, \quad d\phi \cdot d\phi = \frac{1}{\rho^2},$$
 (15)

which yields

$$j = \rho^2(\alpha \cdot d\phi). \tag{16}$$

Solving for x and y in the system of equations (7) and (13) and replacing ρ with ρ_0 for integration on circles centered at the origin, we have

$$x = \frac{z + z^*}{2} = \frac{1}{2} \left(z + \frac{\rho_0^2}{z} \right), \qquad y = \frac{1}{2dxdy} \left(z - \frac{\rho_0^2}{z} \right).$$
 (17)

On those circles, functions of x and y become functions of z —not also z^* . Trigonometric functions reduce to the case just considered since $\cos \phi = x/\rho_0$ and $\sin \phi = y/\rho_0$. We can always write the pull-back f(x,y)dx + g(x,y)dy of α to Cartesian coordinates as

$$k(x,y)dx + g(x,y)dy = wdx, \qquad w \equiv k - gdxdy.$$
 (18)

We proceed to compute j:

$$j = \rho^{2}(wdx) \cdot (\frac{1}{z}dy) = \frac{\rho^{2}}{2} \left[wdx \frac{1}{z}dy + \frac{1}{z}dywdx \right] =$$

$$= \frac{\rho^{2}}{2} \left[w \frac{1}{z^{*}} dxdy + \frac{1}{z} w^{*} dydx \right] = \frac{1}{2} \left[wzdxdy + w^{*}z^{*} (dxdy)^{*} \right] =$$

$$= (wzdxdy)^{(0)} = -(wz)^{(2)}, \tag{19}$$

where the superscripts "0" and "2" stand here for u and v in wz (not in w here). They play the role of real and imaginary parts of wz. For circles centered at pole, z_0 , the role of z will be played by

$$z' \equiv z - z_0. \tag{20}$$

We shall use the term analytic to refer to functions f of z given by a power series, an example being the sine function, where sine is an abbreviation for the series. We shall be interested in meromorphic functions f. They are defined as being analytic in the open set obtained by removing isolated points from the set of definition of f. Such is the case with integer power expansions extended by a finite number of negative power terms, like in the quotient of the sine function by a polynomial. The zeroes of the polynomial are called the poles of the function. In any quotient of functions, the zeroes of the denominator are poles (i.e. points of divergence) of the quotient function, except possibly if the numerator also has a zero at the same point.

Assume that w admits or directly is a series of integer powers (positive, zero and negative) of z' (Fractional powers are not periodic over a circle!). If circling just a pole of first order, we have

$$\oint \alpha = \lim_{\rho_0 \to 0} \oint j(\rho_0, \phi) d\phi = -2\pi \lim_{z \to z_0} [(z - z_0)w]_c^{(2)}], \tag{21}$$

the subscript c referring to the constant term in the series for $[(z-z_0)w]^{(2)}$.

For poles of arbitrary (integer) order, m, that limit does not pick the constant coefficient of the series for $(z - z_0)w$. We shall later consider the standard way of picking that term in the Cauchy calculus. It is worth recalling that, for most integrals of interest, we can proceed with the known alternative that follows.

For a given function $\mathfrak{F}(z)$, let m be the order (i.e. the smallest positive integer such that $\lim_{z\to z_i} \mathfrak{F} \cdot (z-z_i)^m$ is a number a_m different from zero). If

$$\mathfrak{F} - \frac{a_m}{z^m} \tag{22}$$

still has a pole, it is of order p not higher than m-1. We then compute a_p , and so on, until we reach the constant term. It may be zero in particular.

2.3 On applying the theorem of residues

In dealing with integrals on the whole real line, the usual first step in the application of the theorem of residues is the obvious equality

$$\int_{-\infty}^{+\infty} H(x)dx = \int_{-\infty}^{+\infty} wdx,$$
(23)

where w is defined as H(z). If H(z) goes sufficiently fast to zero on a semicircle Γ at the infinity of the upper or lower half of the real plane, we use it to make with the x axis a closed curve.

Consider, for instance, the integral

$$\int_{-\infty}^{+\infty} \frac{1}{(x^2+1)^2} dx. \tag{24}$$

The poles are $z = \pm dxdy$, of order m = 2, and $1/(z^2 + 1)^2$ is clearly meromorphic. We shall later compute it through Cauchy's integral formula, but, if we want to use the theorem of residues, we compute a_2 at z = dxdy:

$$a_2 = \lim_{z \to dxdy} \frac{(z - dxdy)^2}{(z^2 + 1)^2} = \lim_{z \to dxdy} \frac{(z - dxdy)^2}{(z - dxdy)^2(z + dxdy)^2} = -\frac{1}{4}.$$
 (25)

 $(\mathfrak{F} - \frac{a_2}{z'^2})$ will now have a pole of first order at z = dxdy, i.e. at the point (0,1). In order to minimize clutter when computing $z'(\mathfrak{F} - \frac{a_2}{z'^2})$, we excep-

tionally use the symbol i as abbreviation for dxdy. Hence

$$z'\left(\mathfrak{F} - \frac{a_2}{z'^2}\right) = (z - i)\left[\frac{1}{(z^2 + 1)^2} + \frac{1}{4(z - i)^2}\right] =$$

$$= \frac{z^3 + iz^2 + 5z - 3i}{4(z^2 + 1)^2} = \frac{z + 3i}{4(z + i)^2}$$
(26)

The factor of i in the limit $z \to i$ of this expression is -1/4. Multiplying by -2π , we obtain the value $\pi/2$ for the integral (24).

Up to this point in this section, we have assumed the integer powers expansion. It is a trivial matter to show that these expansions satisfy the Cauchy Riemann conditions,

$$u_{,x} = v_{,y} \qquad \qquad u_{,y} = -v_{,x} \tag{27}$$

which are independent of each other.

Suppose that, rather than generating w = H(z) by replacing x with z in H(x), we originally had a closed 1-form α that we were to integrate on a closed curve in the plane. For α to be closed, we only need k,y=g,x. We rewrite (18) as

$$wdx \equiv k(x,y)dx + g(x,y)dy = (k - gdxdy)dx.$$
 (28)

The identifications

$$u \equiv k, \qquad v \equiv -q \tag{29}$$

follow. Condition $k_{,y} = g_{,x}$ is only the second of conditions (27). The method of residues is not justified for all closed differential forms but only for those that also satisfy $k_{,x} = -g_{,y}$, since our argument applied only to functions that are integer power series, even if not expressed as such (remember that, for example, *sine* is an abbreviation for a particular series).

3 Integral formulas

3.1 Cauchy's special integral formula

Assume that f(z) does not have poles in the contour and surface enclosed, where it is assumed to be continuous. At any point z_0 inside, we have, by the theorem of residues,

$$0 = \oint \frac{f(z) - f(z_0)}{z - z_0} dx,$$
 (30)

since $f(z) - f(z_0)$ is the coefficient of the term of order -1. Assume further that $f(z_0)$ is a 2-form, which is the reason why we put "special" in the title. Although dx equals dz, we prefer to use f(z)dx over f(z)dz to help readers remember this special case. The f(z)dz in this paper is not equivalent to the f(z)dz of standard complex variable calculus. In the next paper, we shall have something equivalent, but not under the notation f(z)dz.

From (30) follows that

$$\oint \frac{f(z)}{z - z_0} dx = \oint \frac{f(z_0)}{z - z_0} dx = \oint \frac{f(z_0) dx dy}{z - z_0} dy.$$
(31)

Since $f(z_0)dxdy$ now is a 0-form, we can pull it out of the integral to further obtain

$$\oint \frac{f(z)}{z - z_0} dx = f(z_0) dx dy \oint \frac{1}{z - z_0} dy' = f(z_0) dx dy \oint d\phi' = 2\pi f(z_0) dx dy,$$
(32)

where we have used that dy = dy' (If $f(z_0)$ were a 0-form, we would be dealing with an integral over ρ , which is zero). Cauchy's integral formula then follows:

$$f(z_0) = \frac{1}{2\pi dx dy} \oint \frac{f(z)}{z - z_0} dx,$$
(33)

Consider for example the integration

$$\int_{-\infty}^{+\infty} \frac{1}{(x^2+1)} dx = \oint \frac{1}{z^2+1} = \oint \frac{\frac{1}{z+dxdy}}{z-dxdy} dx$$
 (34)

on the upper half plane, where $z_0 = dxdy$. The evaluation of 1/(z + dxdy) at z = dxdy is a 2-form. The application of (32) is justified. We obtain

$$\int_{-\infty}^{+\infty} \frac{1}{(x^2+1)} dx = 2\pi dx dy \left| \frac{1}{z+dx dy} \right|_{z=dx dy} = \frac{2\pi dx dy}{2dx dy} = \pi.$$
 (35)

In a circle of radius unity centered at z=0, the integral

$$\oint \frac{1}{z(z-\pi)} dz \tag{36}$$

is imaginary. The Cauchy integral formula of this formalism does not apply here because $1/(z-\pi)$ is real at z=0.

Finally consider the integral

$$\int_{-\infty}^{+\infty} \frac{e^{itx}}{x^2 + 1} dx. \tag{37}$$

We make a closed curve with the upper semicircle at infinity. It contains the single pole (0,1), which implies z = dxdy. At z = dxdy, the numerator of

$$\dots = \int_{-\infty}^{+\infty} \frac{\frac{e^{tzdxdy}}{z + dxdy}}{z - dxdy} dx. \tag{38}$$

is a 2-form. We apply the theorem and get

$$2\pi dx dy e^{-t} \frac{1}{2dx dy} = \pi e^{-t}. (39)$$

The integrand in (37) is not real, but the integral is.

3.2 Cauchy's special integral formula for derivatives

We rewrite Eq. (33), which is valid if $f(z_0)$ is a 2-form, as

$$f(z) = \frac{1}{2\pi dx dy} \oint \frac{f(\zeta)}{\zeta - z} d\chi. \tag{40}$$

Clearly

$$\frac{\partial f(z)}{\partial x} = \frac{1}{2\pi dx dy} \oint \frac{\partial}{\partial x} \frac{f(\zeta)}{\zeta - z} d\chi = \frac{1}{2\pi dx dy} \oint \frac{f(\zeta)}{(\zeta - z)^2} d\chi \tag{41}$$

and, by successive application,

$$\frac{\partial^n f(z)}{\partial x^n} = \frac{n!}{2\pi dx dy} \oint \frac{f(\zeta)}{(\zeta - z)^{n+1}} d\chi,\tag{42}$$

which we rewrite as

$$\oint \frac{f(z)}{(z-z_0)^{n+1}} dx = \frac{2\pi dx dy}{n!} \left(\frac{\partial^n f(z)}{\partial x^n}\right)_{z=z_0}.$$
(43)

Consider again the integration of (24) around the pole (0, 1). In our real formalism, $z_0 = dxdy$.

$$\oint \frac{dx}{\left(z^2+1\right)^2} = \oint \frac{\frac{1}{\left(z+dxdy\right)^2}}{\left(z-dxdy\right)^2} dx.$$
(44)

We identify n = 1 and $f(z) = (z + dxdy)^{-2}$ so that

$$\oint \frac{1}{(z^2+1)^2} dx = 2\pi dx dy \left[\frac{\partial}{\partial x} \frac{1}{(z+dx dy)^2} \right]_{z=dx dy} = \frac{\pi}{2}.$$
(45)

4 Other theorems

In the calculus of complex variable, Cauchy's integral formulas are the gate to the Laurent series, the theorem of residues and the computation of the residue for poles of order higher than one. We have already covered the theorem of residues. We assumed at an early point that we would consider only functions defined by power series (including negative exponents), but those function will be given to us in abbreviated form, like saying $\sin x$ without stating the series. Occasionally we may want or wish to have the series explicitly. In the Weierstrass approach that we advocate here, the perspective is somewhat different from the standard one as we do not need to use Cauchy's integral formulas.

Given a function f(x+ydxdy) that is defined by a power series (like, say, a sine function divided by a polynomial which has zero of order m at z_0), it will obviously be given by a power series of the form

$$f(z) = \frac{a_{-m}}{z'^m} + \frac{a_{-m+1}}{z'^{m-1}} + \dots + \frac{a_{-1}}{z'} + a_0 + a_1 z' + a_0 z'^2 + \dots$$
 (46)

where $z' = z - z_0 = (x + ydxdy) - (x_0 + ydxdy)$. The function $z'^m f(z)$ is analytic,

$$z'^{m} f(z) = a_{-m} + a_{-m+1} z' + \dots + a_{-1} z'^{m-1} + a_{0} z'^{m} + \dots = \sum_{n=0}^{\infty} b_{n} z'^{n}.$$
 (47)

We now consider $z'^m f(z)$ as a function in (x, y). It is clear that

$$b_n = \frac{1}{n!} \lim_{z \to z_0} \frac{\partial^n [z'^m f(z)]}{\partial x^n} = a_{n-m}.$$

$$\tag{48}$$

That is much clearer than the expression for the coefficients of the Laurent expansion in terms of the integrals in the Cauchy integral formulas. The Laurent series then takes the form

$$f(z) = \sum_{n=0}^{\infty} z'^{(n-m)} \frac{1}{n!} \lim_{z \to z_0} \frac{\partial^n [z'^m f(z)]}{\partial x^n}.$$
 (49)

Finally, the formula for the residual when a pole is of order m is a particular case of (48), namely

$$a_{-1} = \frac{1}{(m-1)!} \lim_{z \to z_0} \frac{\partial^{m-1} [z'^m f(z)]}{\partial x^{m-1}}.$$
 (50)

5 Concluding remarks

We have touched only the elementary part of the calculus of complex variable, which meets the practical interests of most physicists. But it still should have foundational interest for mathematicians. Those interests would not have been enough motivation to write this paper. My most important motivation is what I see as missed opportunity by physicists in overlooking the worth of the Kähler calculus for physics.

When endowed with the rich structure conferred by Clifford algebra and Kähler differentiation, differential forms are the words in a unified language to deal with the requirements of mathematical physics. Their use for the foundations of quantum mechanics is evident in Kähler's cited paper (no negative energy antiparticles, spin without internal space, etc.), which unfortunately is in German. In order to minimize the need for sufficient knowledge of that language to follow the arguments through the formulas, it is helpful to be familiar with the ways of É. Cartan in dealing with differential forms, since Kähler's style is essentially the same. This style morphed in mid 20th century into the modern one. Though the recommendation is self-serving, some readers may still wish to consider the recent book on differential geometry by this author [3] in order to learn to compute with differential forms in Cartan and Kähler's style.

References

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